CSCI 699: Privacy Preserving Machine Learning - Week 2

Differential Privacy

Recap

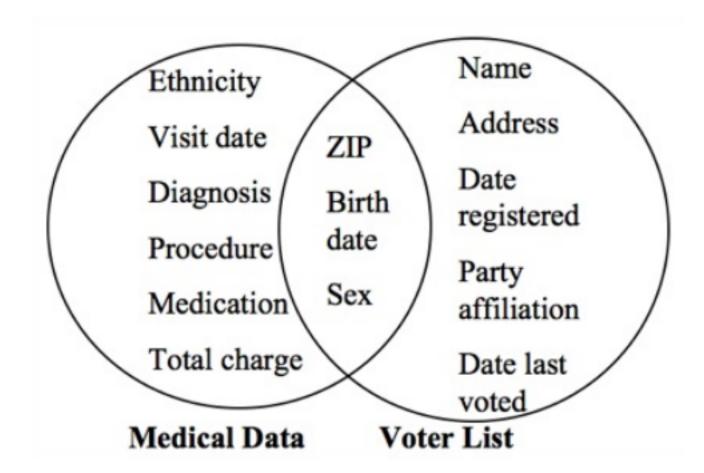
- We saw many definitions of privacy
 - De-identification / suppression
 - K-anonymity
 - L-diversity
- We saw none of them really protected privacy and were easily broken
- Hinted at a more widely accepted definition.

Takeaways

Requirements for privacy definition

- Unaffected by auxiliary information: we should not be able to combine extra data to undo privacy.
- Composition: We should understand what happens when data is continuously released.

 Today we will come with such a privacy definition.





Quantifying Privacy Leakage

Attempt 2

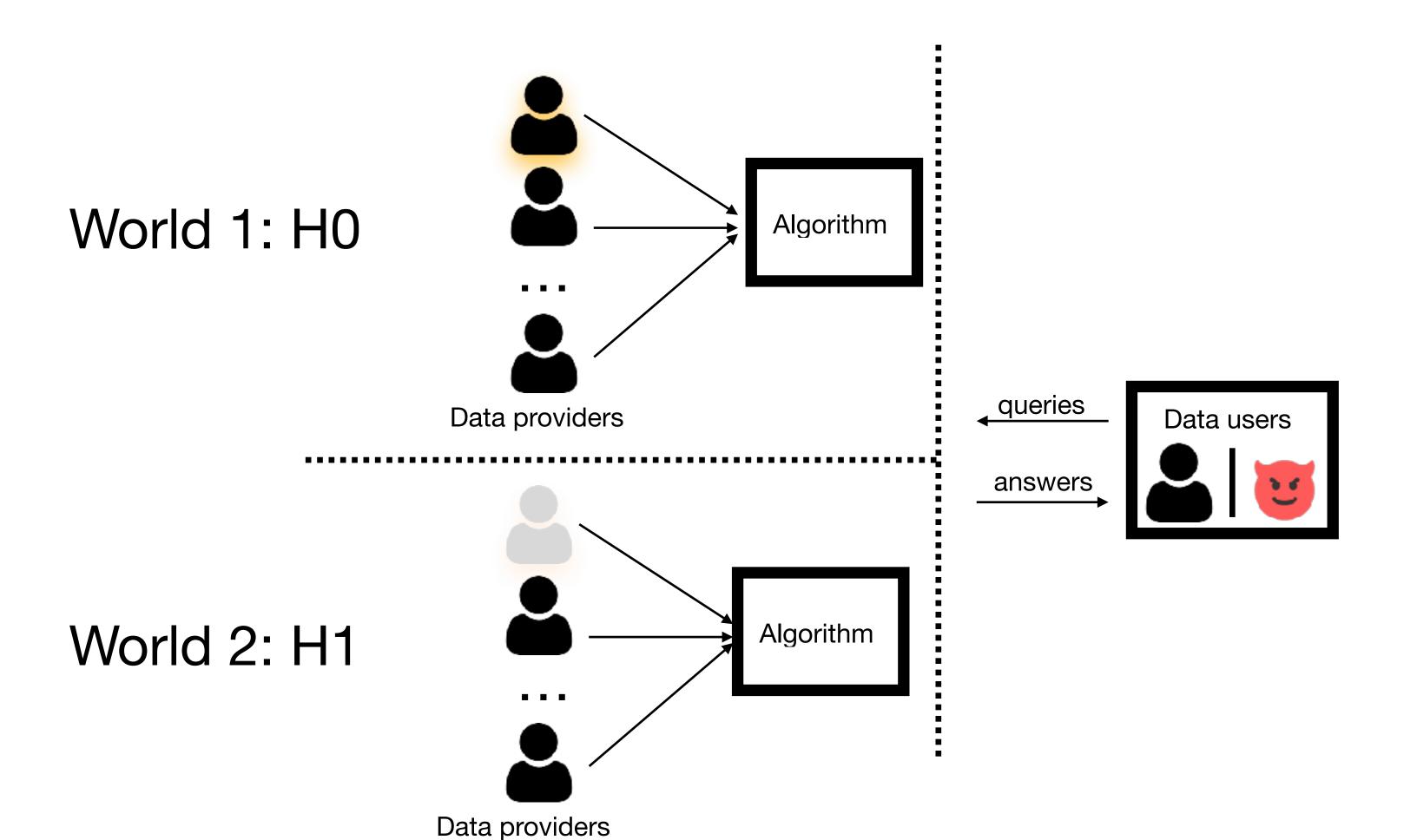
Relative Privacy: quantify new information leaked

"An analysis of a dataset is private if what can be learned about an individual in the dataset is not much more than what would be learned if the same analysis was conducted without them in the dataset"

- Intuition: Whether Bob is present in the data or not, the answer should not change much.
- Then, from looking at the answer, we will not learn whether Bob was present in the data or not.
- Gives Bob plausible deniability.

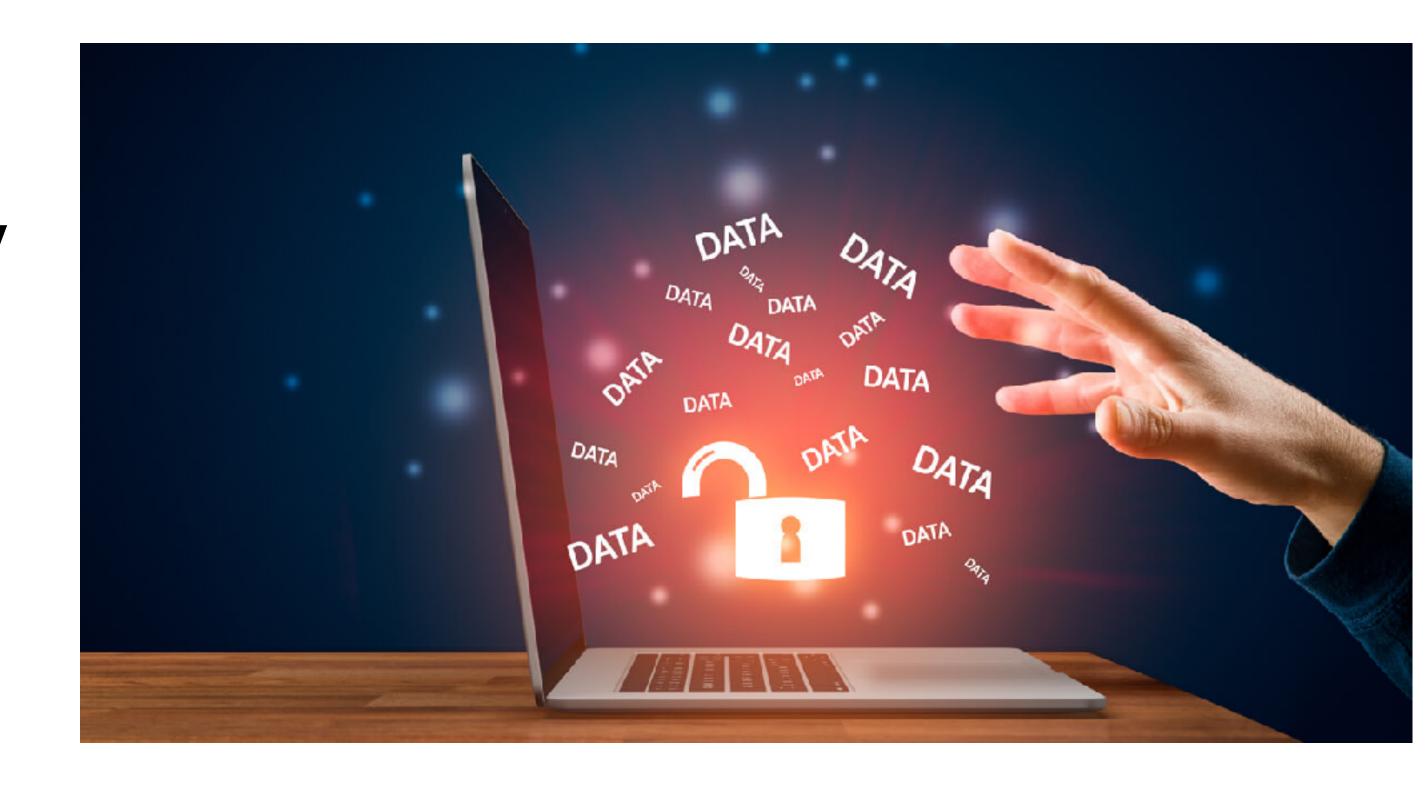
Quantifying Privacy Leakage

Attempt 2

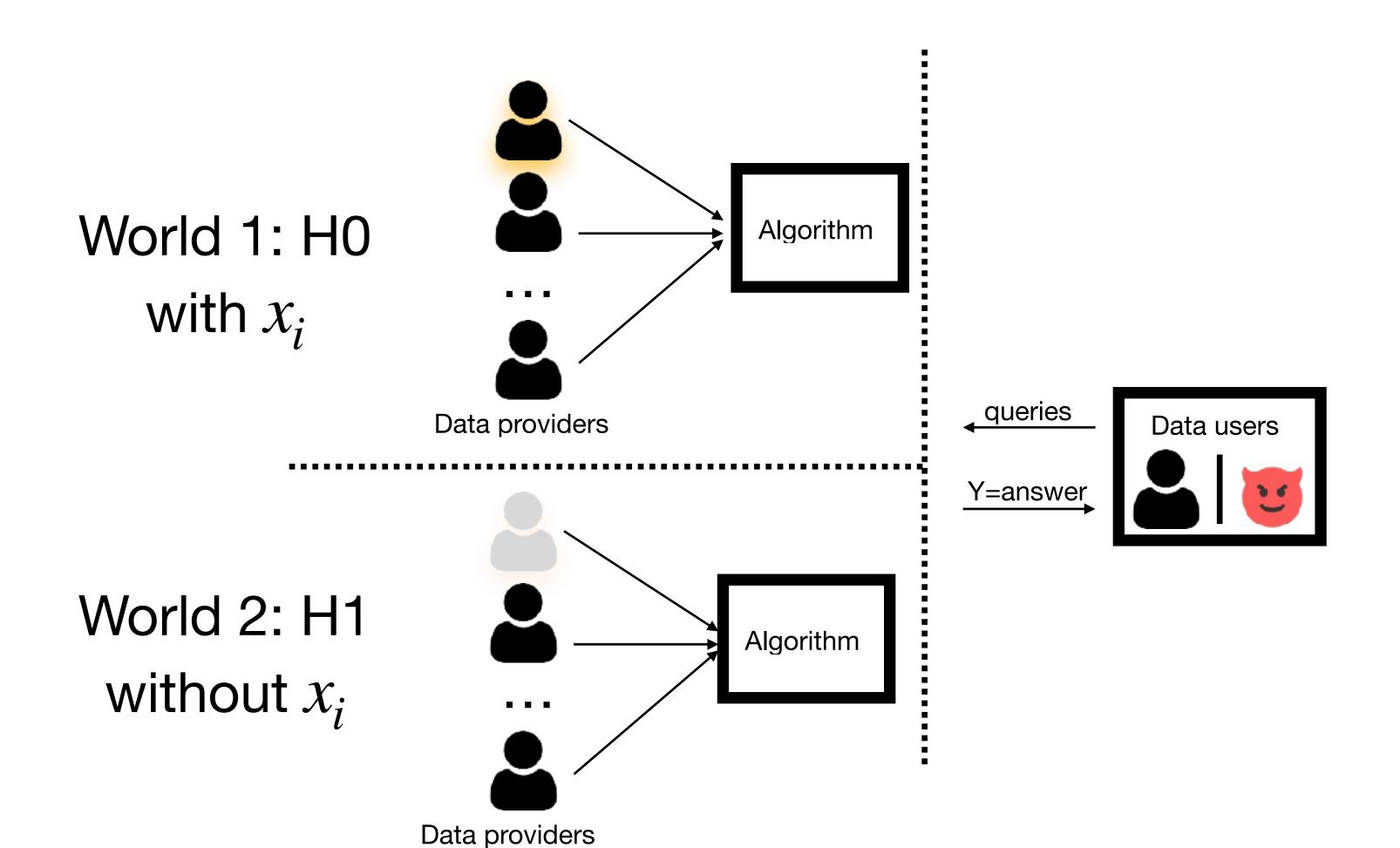


- In world 2 only Bob is removed/ replaced.
- Now from the answer, how easily can guess the correct world?

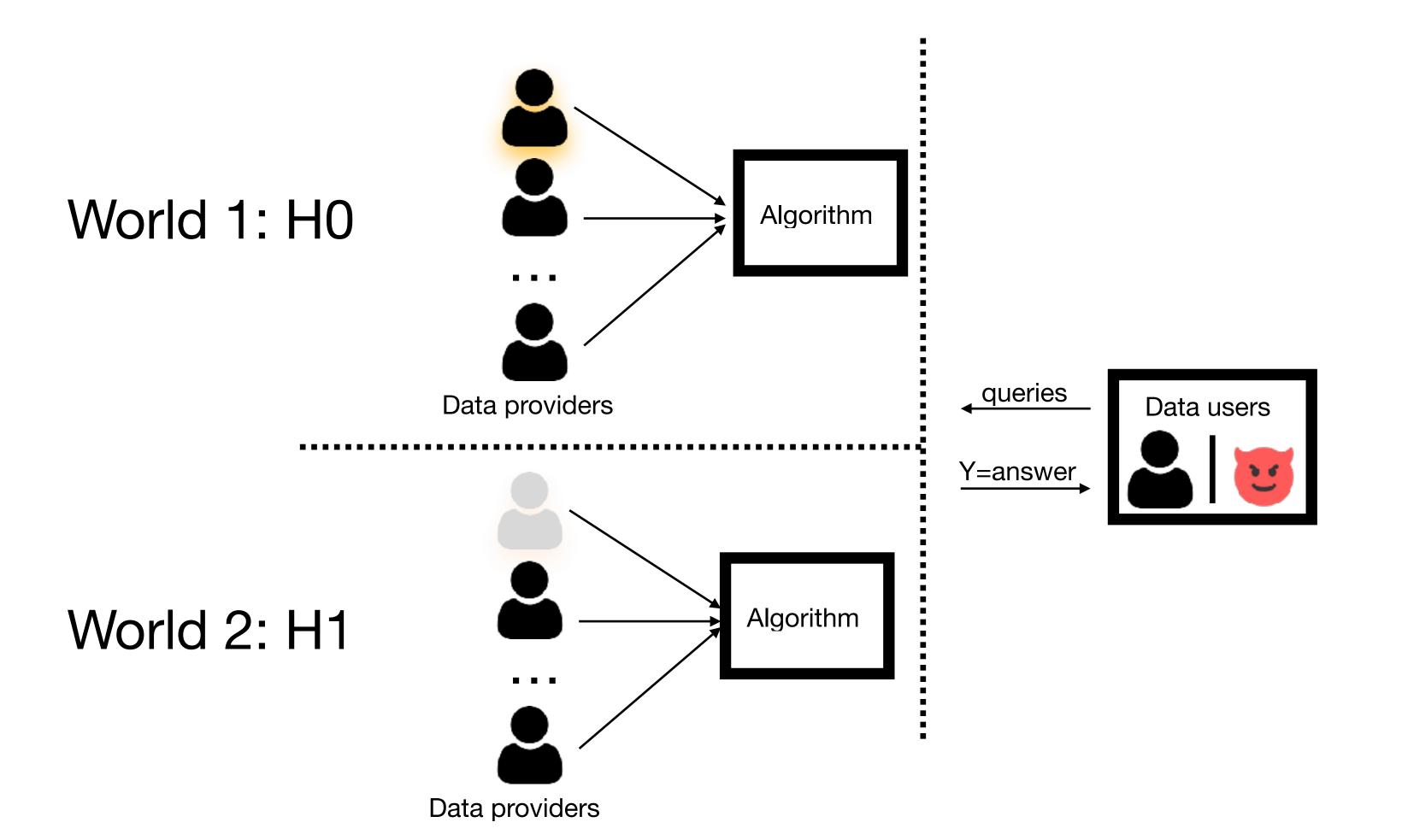
Quantifying Privacy Leakage



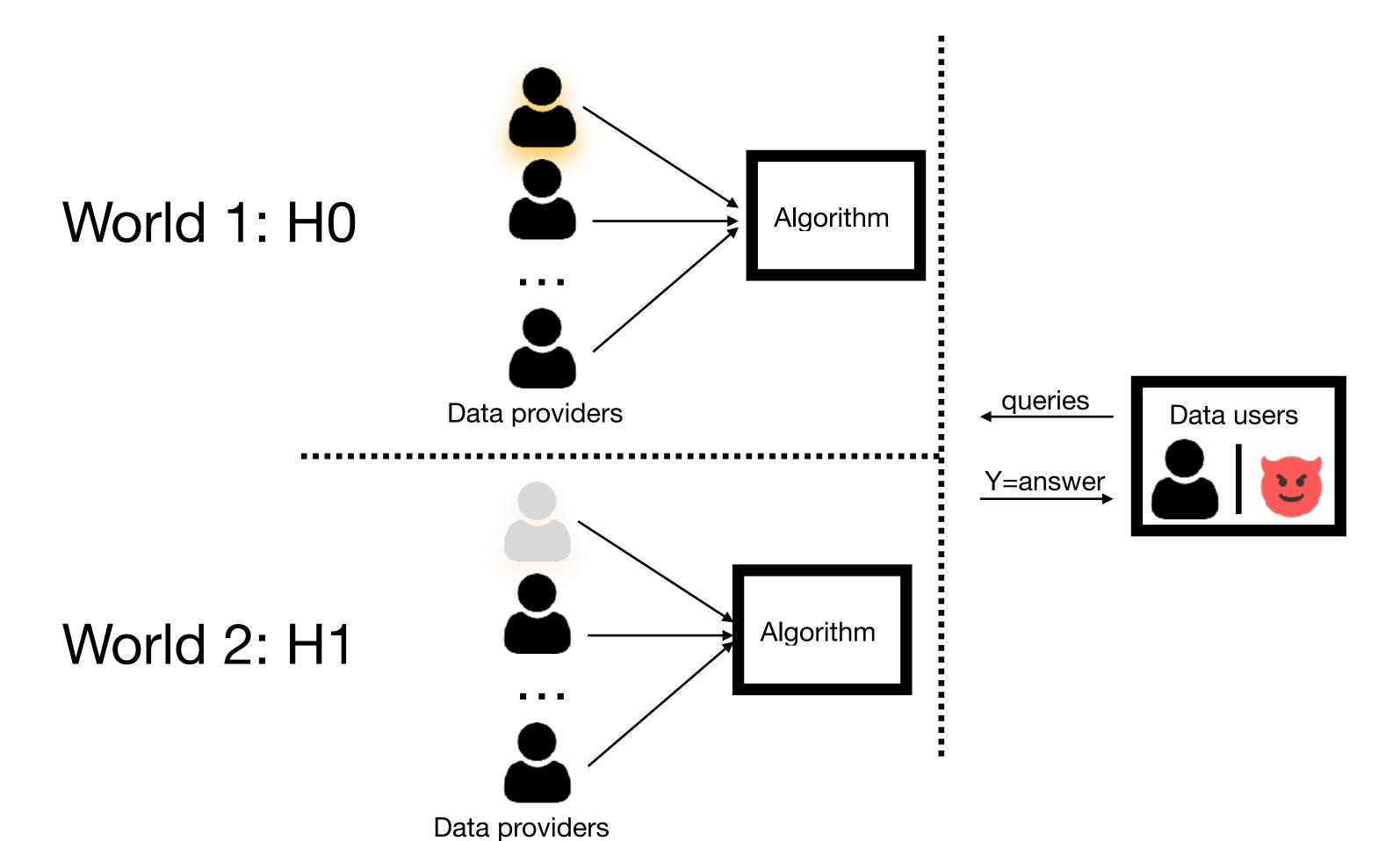
As a definition of privacy



- We know everything about the algorithm and even D, x_i
- Only 1 bit unknown H_0 or H_1 ?
- We observe an output Y
- Need to guess if it came from H0 or H1

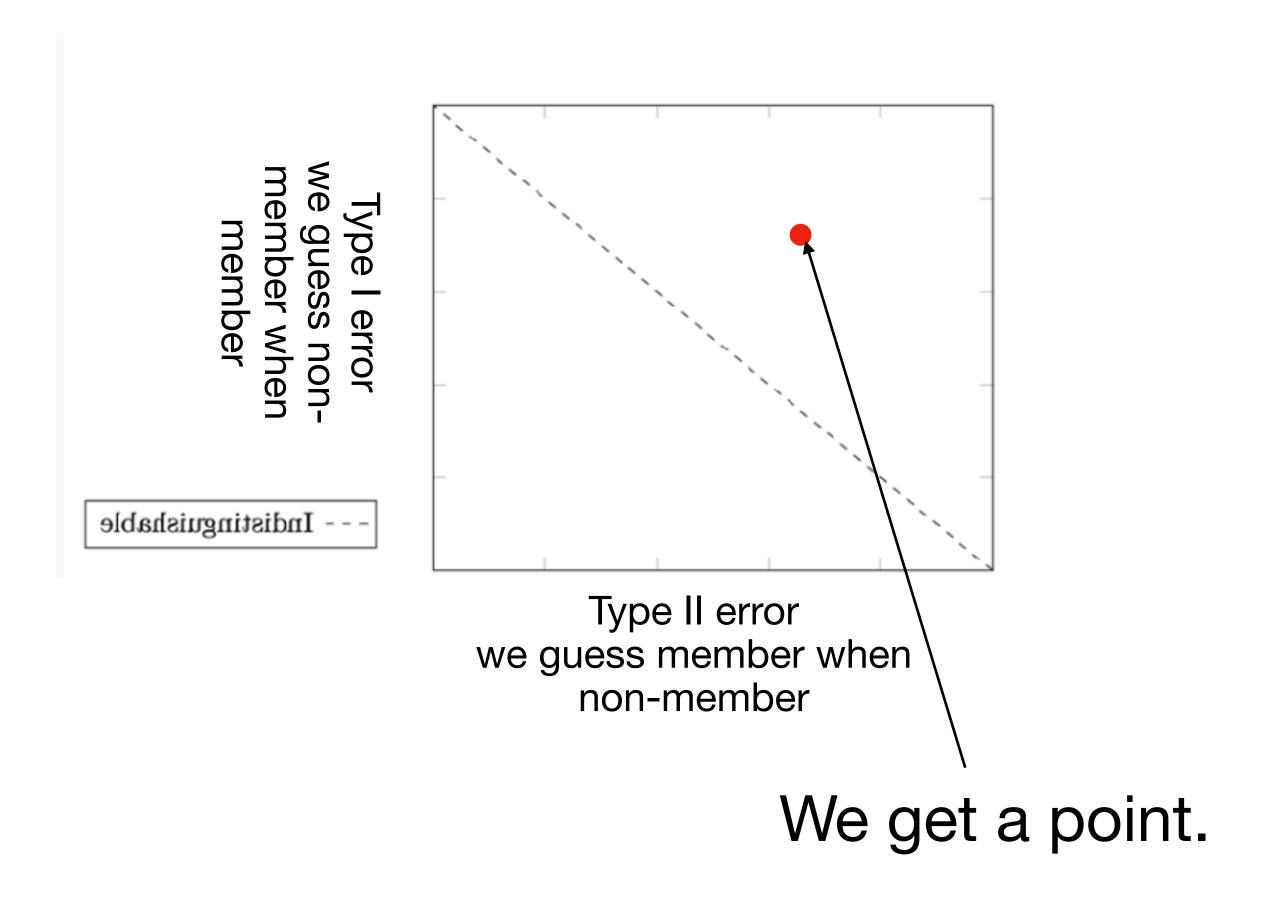


 Can a deterministic algorithm be private?



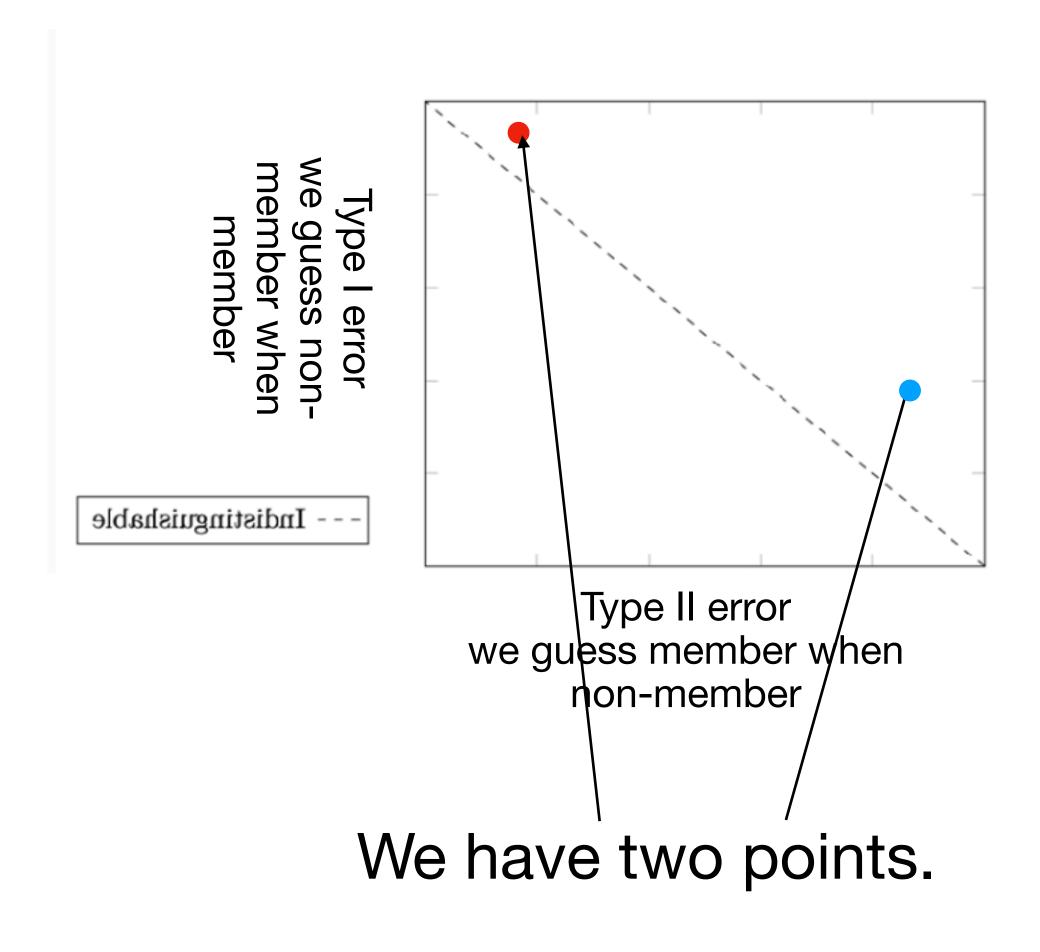
- Can a deterministic algorithm be private?
- No adversary can simply compute Y = f(D) or $f(D \setminus x_i)$?
- Need randomness
 adversary will
 have type I and
 type II errors

Quantifying attack success



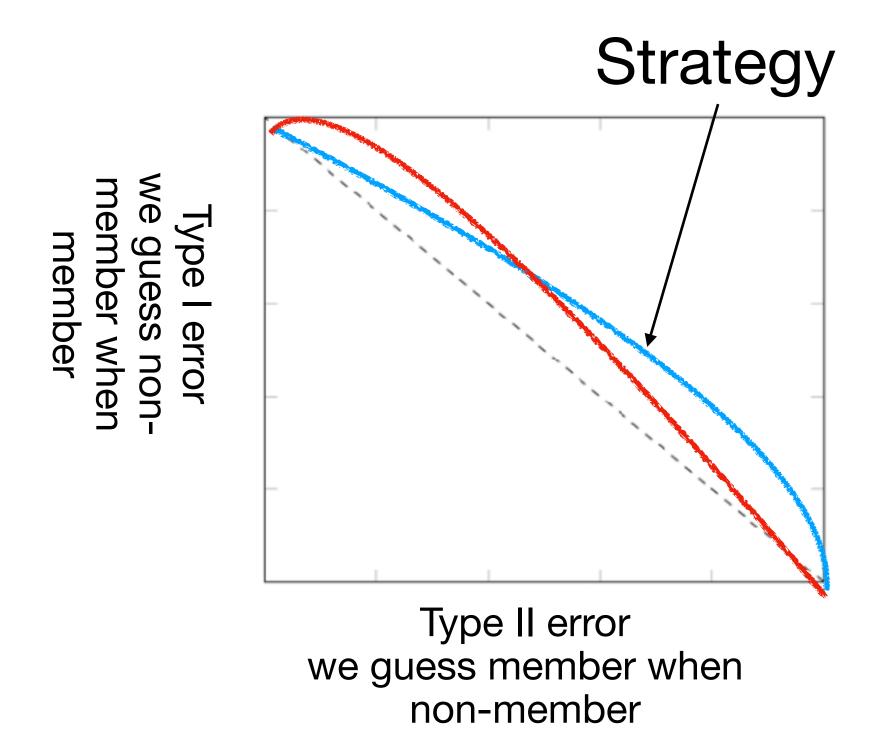
- Suppose we run multiple runs
- Count the number of times the adv guesses H0 vs H1 correctly
- We can compute Type I and Type II errors.

Quantifying attack success



- Suppose we have two algorithms, each with different type I and type II errors.
- Which one has more privacy leakage?

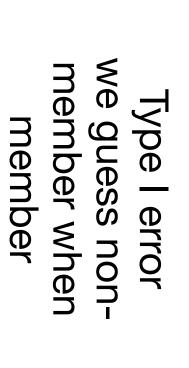
Tradeoff curve

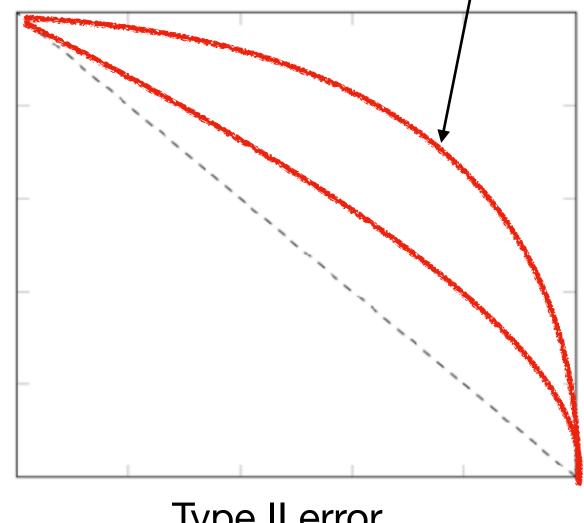


- Depends on what we care
- E.g. its important not to miss anyone e.g. sending cat ads to pet owners - coverage
- Not ok if we are accusing them of a crime - precision much more important
- Impossible to compare individual points - need to compare entire trade off curves.

Comparing tradeoff curves

Better strategy 2



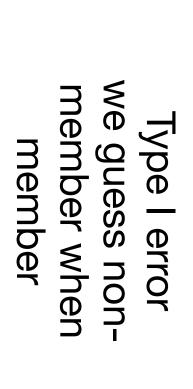


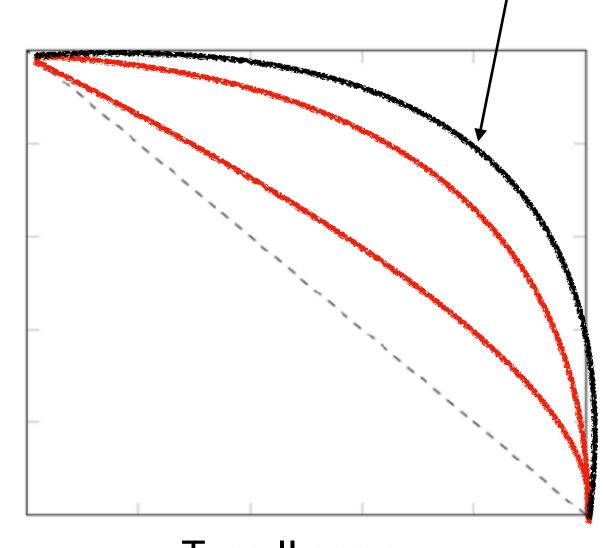
Type II error we guess member when non-member

- Tradeoff curve depends on testing strategy adversary uses.
- Strategy 2is better than Strategy 1 if the curve is uniformly above.
- Higher curve means we've found more privacy leakage

Optimal tradeoff curve

Unknown optimal

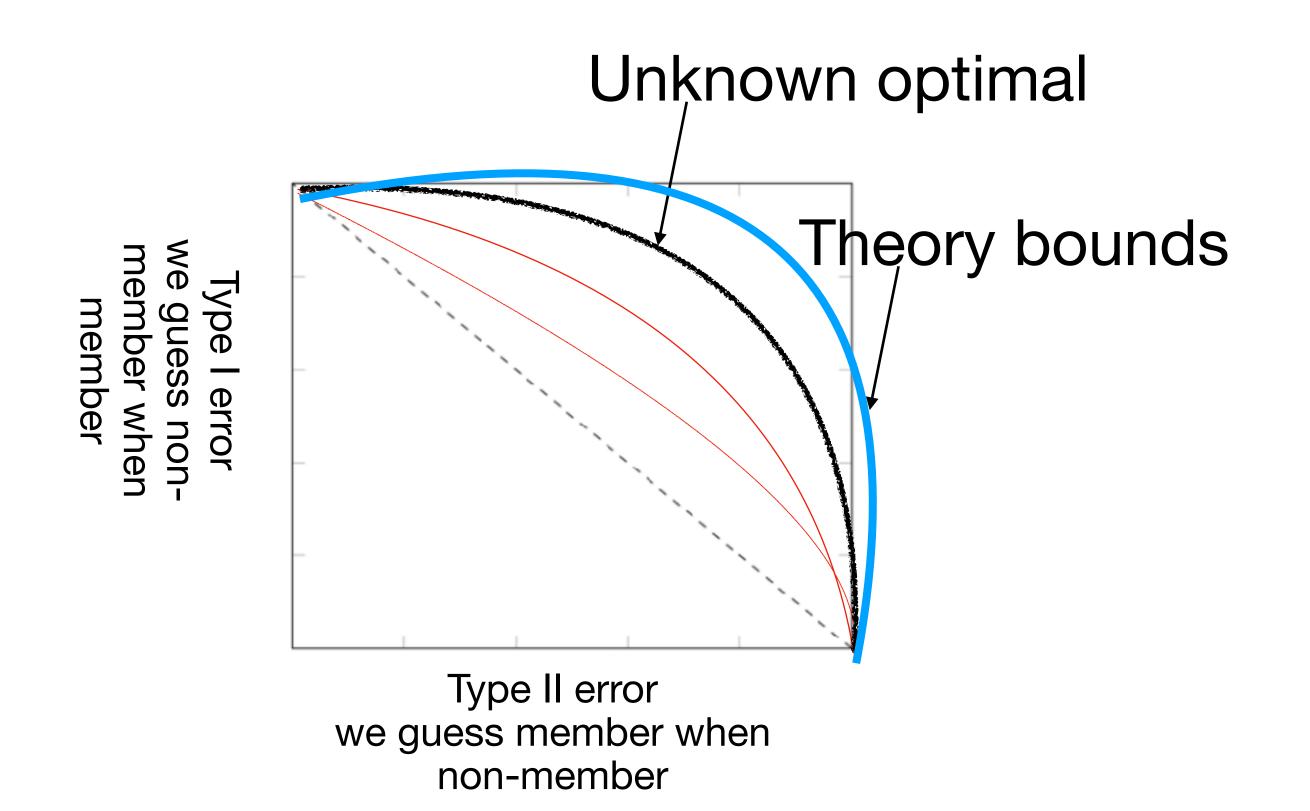




Type II error we guess member when non-member

- There is an optimal strategy
- use this to quantify privacy leakage
- What if no single strategy is best?
- Neyman-Pearson lemma guarantees existence of uniformly most powerful test.

Privacy from tradeoff curve



- Use optimal strategy to quantify privacy
- But empirical tests only give an lower-bound
- Need theory to give upper-bound



Calibrating Noise to Sensitivity in Private Data Analysis

2006

Cynthia Dwork¹, Frank McSherry¹, Kobbi Nissim², and Adam Smith³*

2017 Gödel Prize

Differential privacy is a powerful theoretical model for dealing with the privacy of statistical data. The intellectual impact of differential privacy has been broad, influencing thinking about privacy across many disciplines. The work of Cynthia Dwork (Harvard University), Frank McSherry (independent researcher), Kobbi Nissim (Harvard University), and Adam Smith (Harvard University) launched a new line of theoretical research aimed at understanding the possibilities and limitations of differentially private algorithms. Deep connections have been exposed in other areas of theory (including learning, cryptography, discrepancy, and geometry) and have created new insights affecting multiple communities.

Threat model

- Let χ be a the domain of training data
- A dataset $D \in \chi^n$ is a multiset of n records/rows of χ
- D (sensitive data) ———— algorithm ———— Y (answers)
- Attacker wants to infer some information about $D \in \chi^n$
 - ullet observes Y
 - knows algorithm, domain χ , and potentially more prior information
 - cannot control what attacker knows

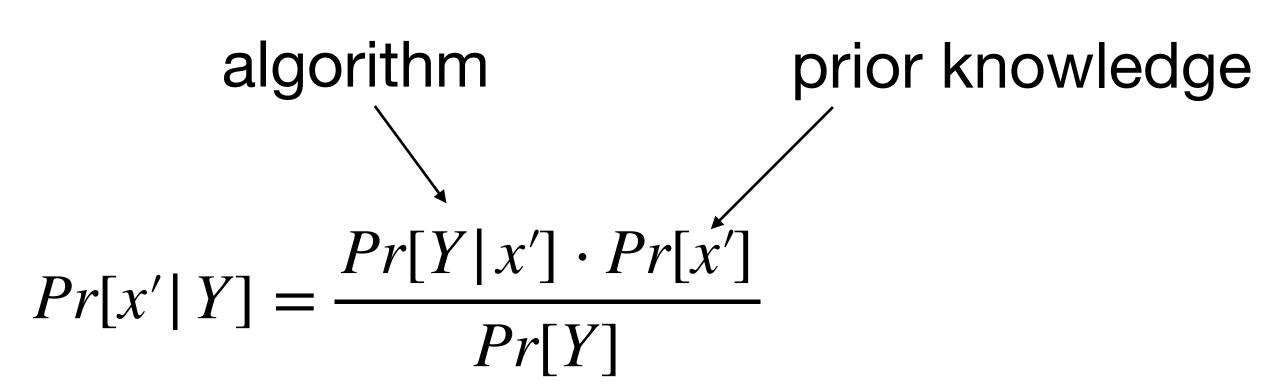
Threat model

- Attacker wants to infer some information about $D \in \chi^n$
 - observes Y, knows algorithm, domain χ , and prior information.
 - can compute likelihood of dataset:

algorithm prior knowledge
$$Pr[D \mid Y] = \frac{Pr[Y \mid D] \cdot Pr[D]}{Pr[Y]}$$

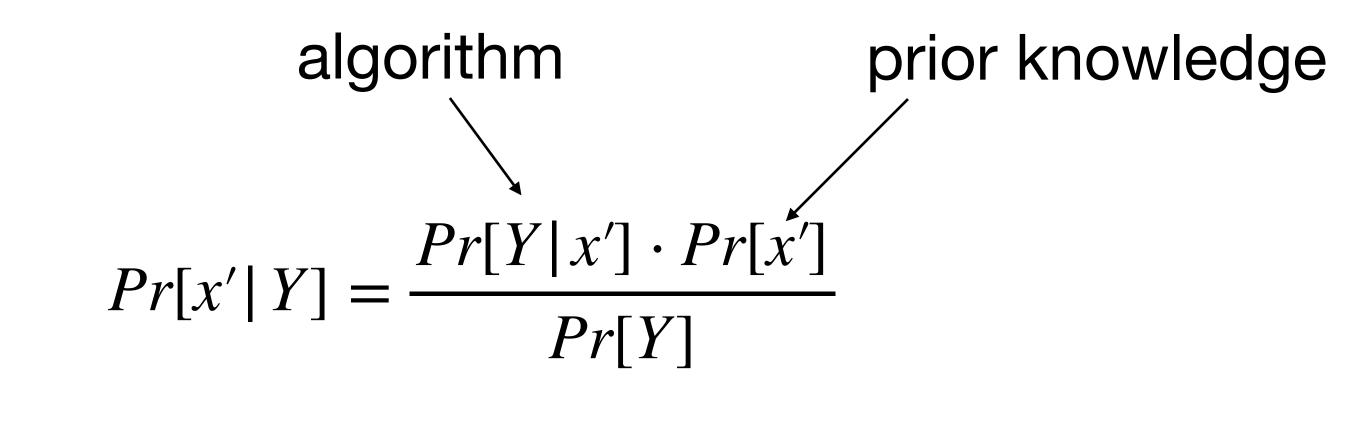
Performing membership inference

- Attacker wants to infer presence of $x \in X$?
 - observes Y, knows algorithm, domain χ , and even $D \setminus x \in \chi^{n-1}$
 - can compute likelihood of x in dataset



Performing membership inference

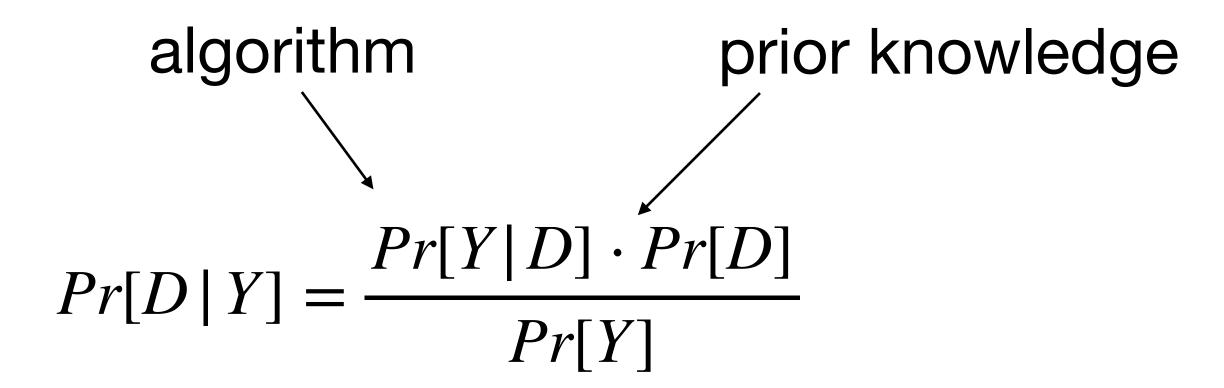
- Attacker wants to infer presence of $x \in X$?
 - can compute likelihood of x in dataset



Can even recover x using max-likelihood

$$\hat{x} = \arg \max_{x'} Pr[Y|x']Pr[x']$$

- Attacker wants to infer some information about $D \in \chi^n$
 - can compute likelihood of seeing some dataset



• We design a private algorithm by controlling Pr[Y|D]

Strict definition

 Perfect relative indistinguishability: For all inputs, the output probability is the same.

$$\forall D, D', y : \Pr[Y = y | \mathscr{D} = D] = \Pr[Y = y | \mathscr{D} = D']$$

- The mechanism does not leak any information about D
- However, achieving it is very hard, does not allow any information about D.

A better definition

 Some indistinguishability: For all neighboring datasets, the output probabilities are bounded.

$$\forall y, \forall \text{ similar } D, D': \qquad \frac{\Pr[Y = y \mid \mathscr{D} = D]}{\Pr[Y = y \mid \mathscr{D} = D']} \leq \text{ constant}$$

- It means by observing any Y, adversary is NOT able to distinguish between inputs x and x' beyond a bounded certainty.
- What does neighboring datasets mean? Depends on use case
 - location positions that are within some range
 - datasets that differ in one individual row (our focus)
 - edit distance 1

Formal definition

ε -Differential Privacy:

An algorithm A satisfies ε -DP if for any neighboring datasets $D, D' \in \chi^n$ and $y \in \mathscr{Y}$

$$\log \frac{Pr[A(D) = y]}{Pr[A(D') = y]} \le \varepsilon \text{ a.s.}$$

- Recall that D (sensitive data) \longrightarrow algorithm $\longrightarrow Y$ (answers)
- So we have, Pr[Y|D] = Pr[A(D) = Y]

Formal definition

ε -Differential Privacy:

An algorithm A satisfies ε -DP if for any similar datasets $D, D' \in \chi^n$ and $y \in \mathscr{Y}$

$$\log \frac{Pr[A(D) = y]}{Pr[A(D') = y]} \le \varepsilon$$

- $\varepsilon = 0$ means perfect privacy
- $\varepsilon \gg 0$ means not private

Source of randomness

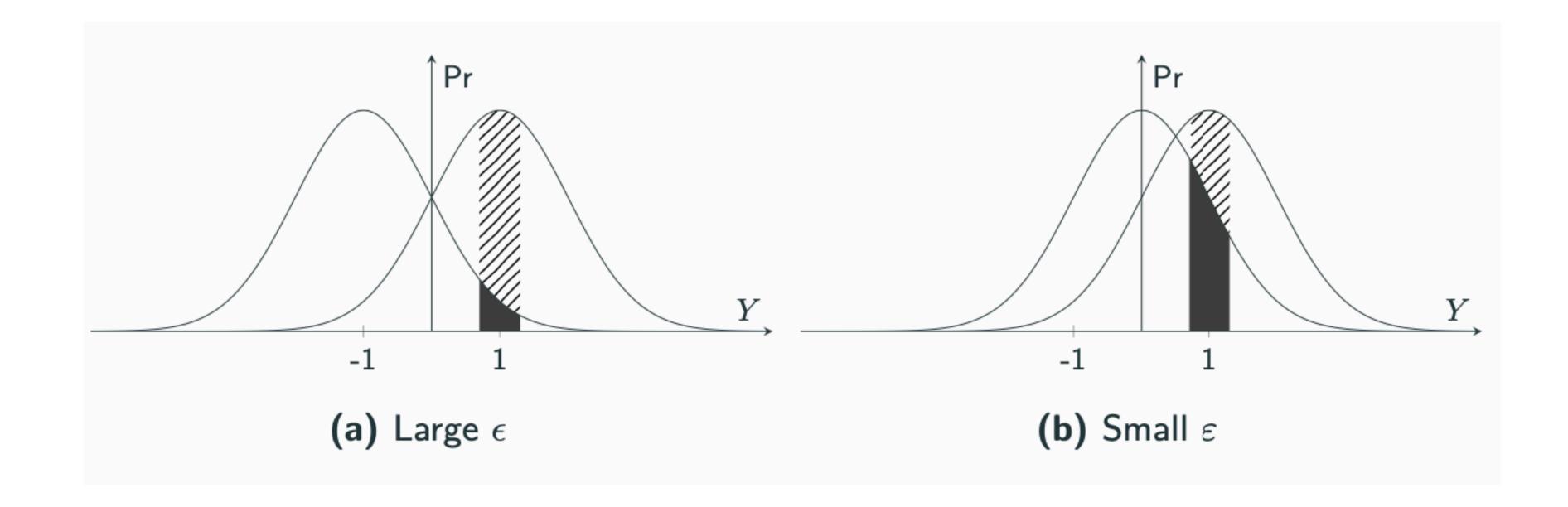
$$\log \frac{Pr[A(D) = y]}{Pr[A(D') = y]} \le \varepsilon \quad a.s.$$

- In Pr[A(D) = y], over what randomness is the probability defined?
 - The randomness of the algorithm?
 - Yes
 - Randomness of the data $D \in \chi^n$?
 - No.
 - We look at all possible values of D, D' i.e. worst case

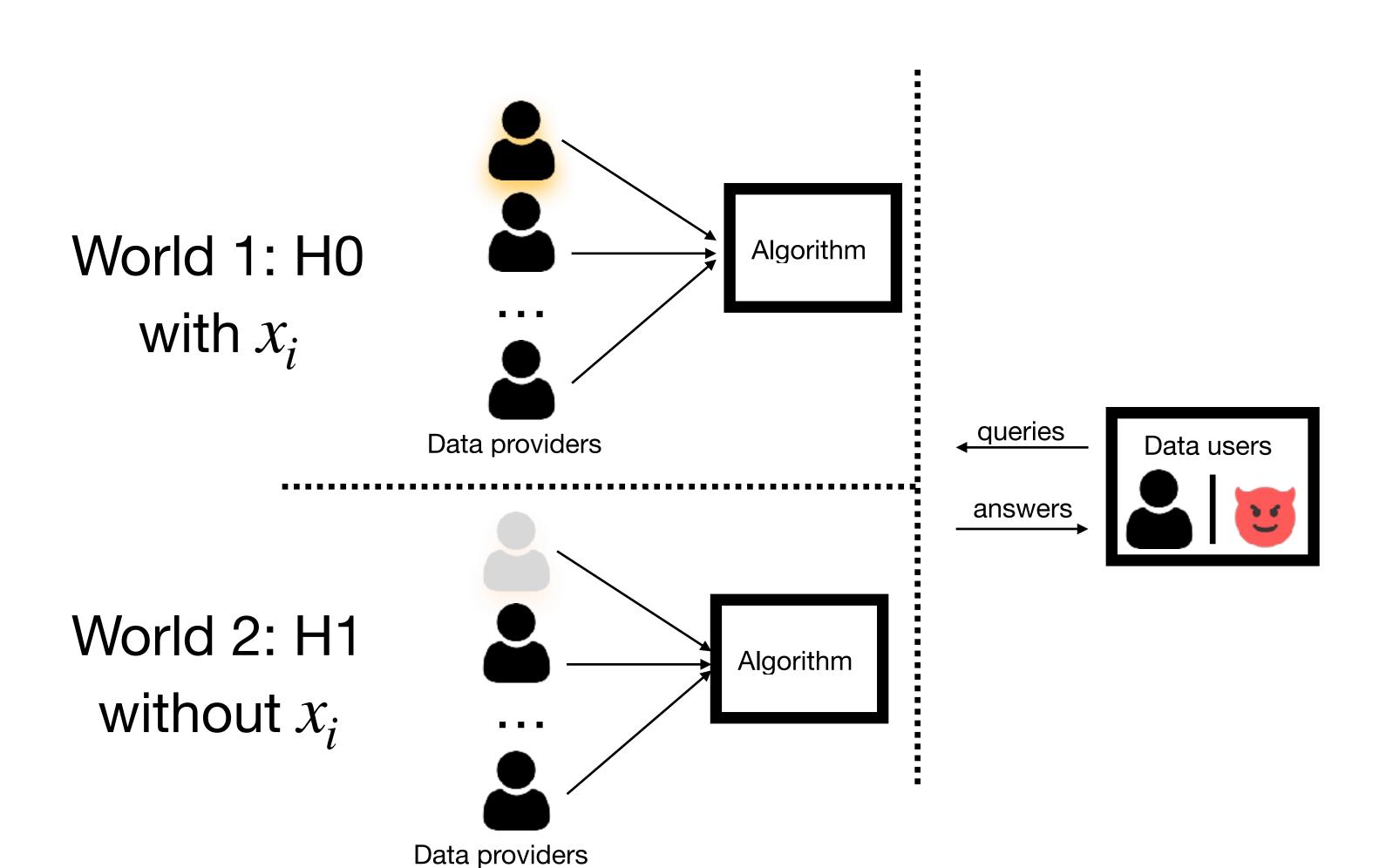
Visual representation

• Consider $D=\langle x_1,\cdots,x_i,\cdots x_n\rangle$, and a similar dataset $D'=\langle x_1,\cdots,x_i,\cdots x_n\rangle$

.
$$\varepsilon\text{-DP means} \ \frac{Pr[A(D)=y]}{Pr[A(D')=y]} \leq \exp(\varepsilon)$$



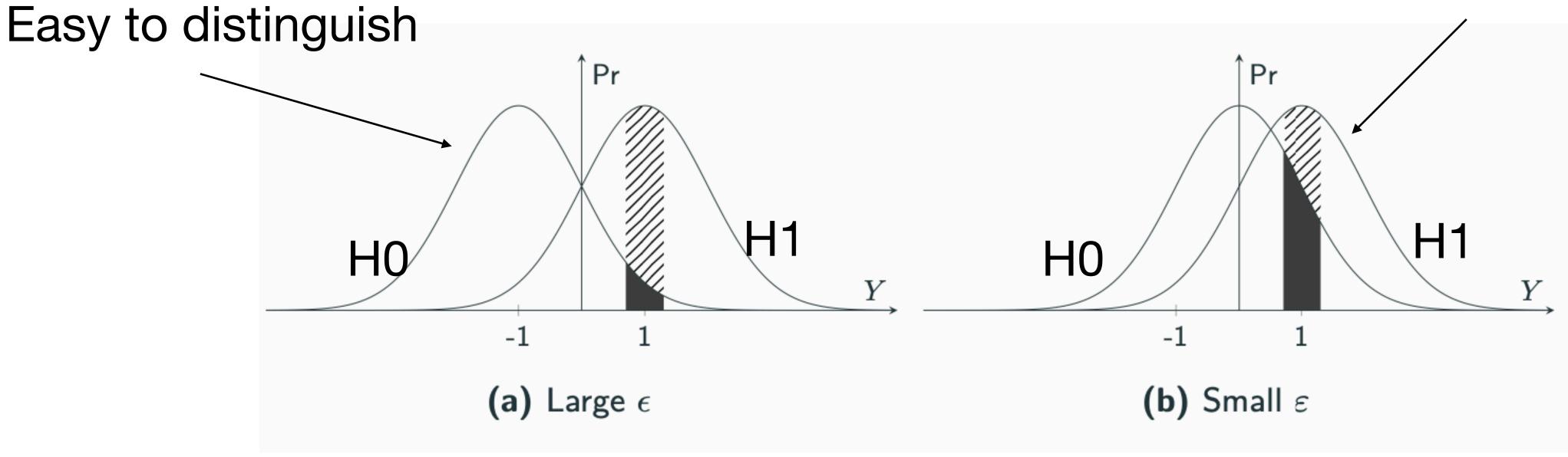
Recall Membership Inference



- We know everything about the algorithm and even $D \setminus x_i$
- We observe an output Y
- Need to guess if it came from H0 or H1

Connection to Membership Inference

Hard to distinguish



- We observe Y = 1.
- Can you guess H0 or H1?

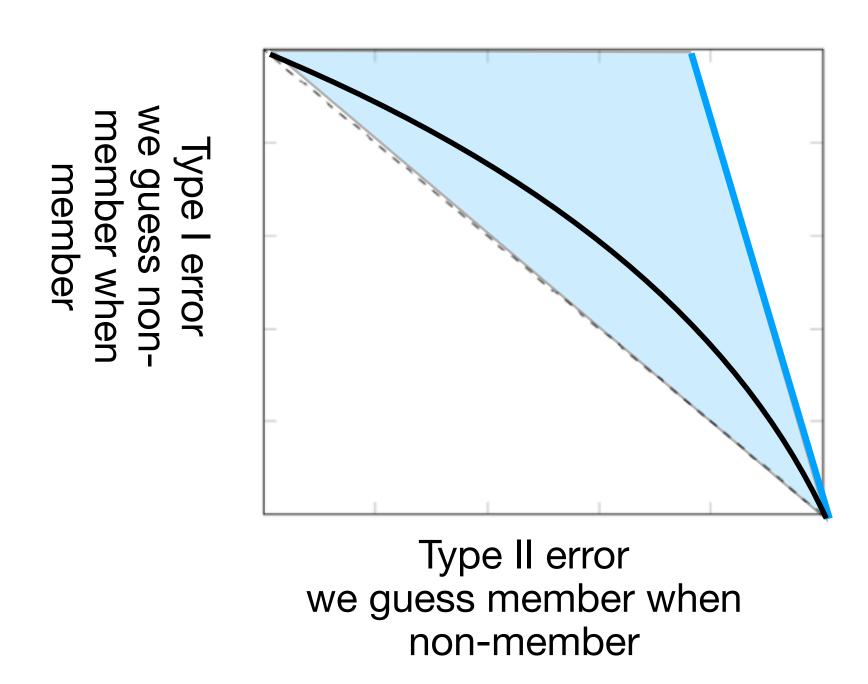
Quantifying connection

Theorem

Suppose A satisfies ε -DP for datasets D, D' which differ by one datapoint. Then, we have

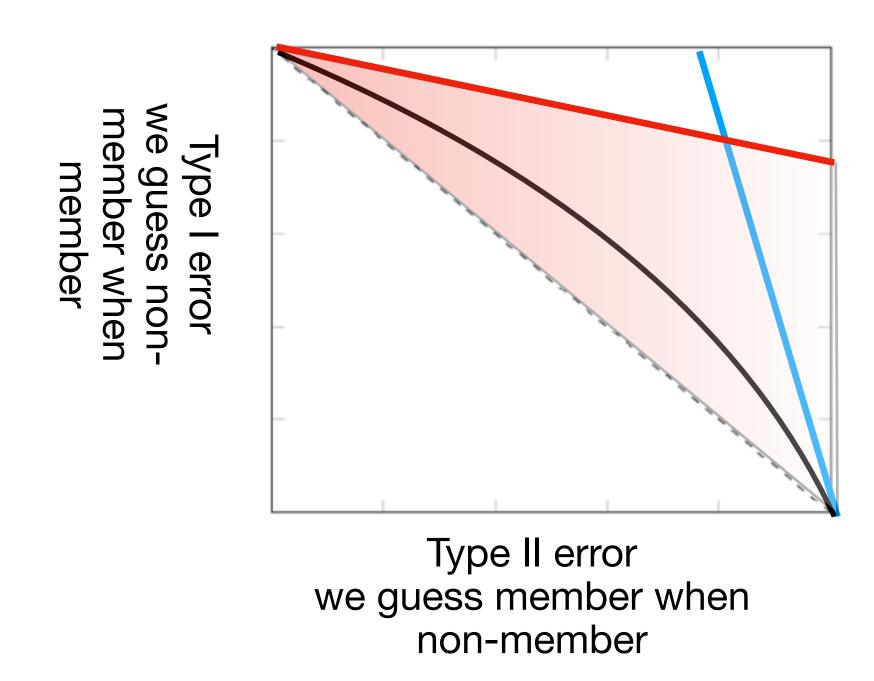
- $Pr[guess H0 | H1] + e^{\varepsilon} Pr[guess H1 | H0] \ge 1$
- $e^{\varepsilon} Pr[\text{guess H0} \mid H1] + Pr[\text{guess H1} \mid H0] \ge 1$
- Type I error = Pr[guess H0 | H1]
- Type II error = Pr[guess H1 | H0]

Visualizing connection



- $Pr[guess H0 | H1] + e^{\varepsilon} Pr[guess H1 | H0] \ge 1$
 - gives us blue line with slope e^{ε}

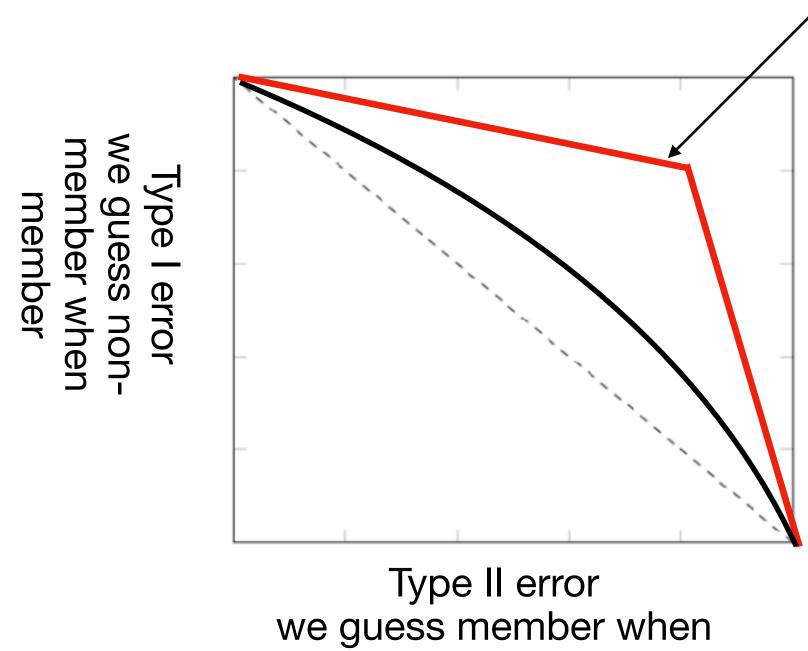
Visualizing connection



- $e^{\varepsilon} Pr[\text{guess H0} \mid H1] + Pr[\text{guess H1} \mid H0] \ge 1$
 - gives the red line with slope $e^{-\varepsilon}$

Visualizing tradeoff curve of DP

Theoretical upper bound

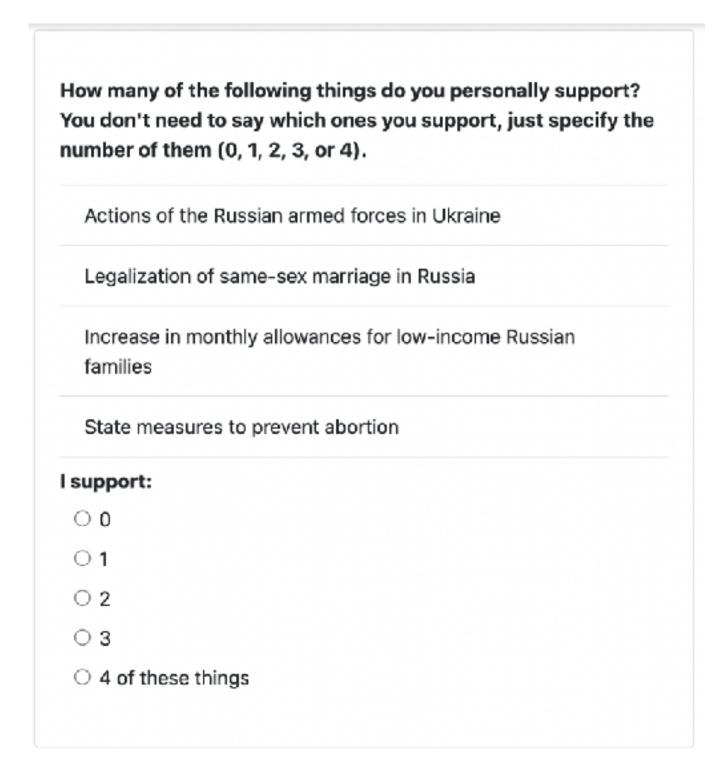


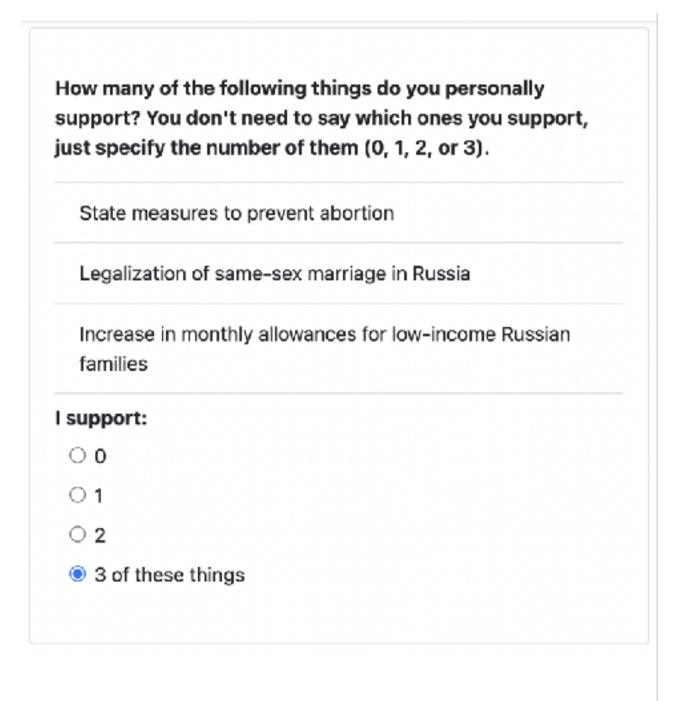
non-member

- $Pr[guess H0 | H1] + e^{\varepsilon} Pr[guess H1 | H0] \ge 1$
 - gives us blue line
- $e^{\varepsilon} Pr[\text{guess H0} \mid H1] + Pr[\text{guess H1} \mid H0] \ge 1$
 - gives the red line

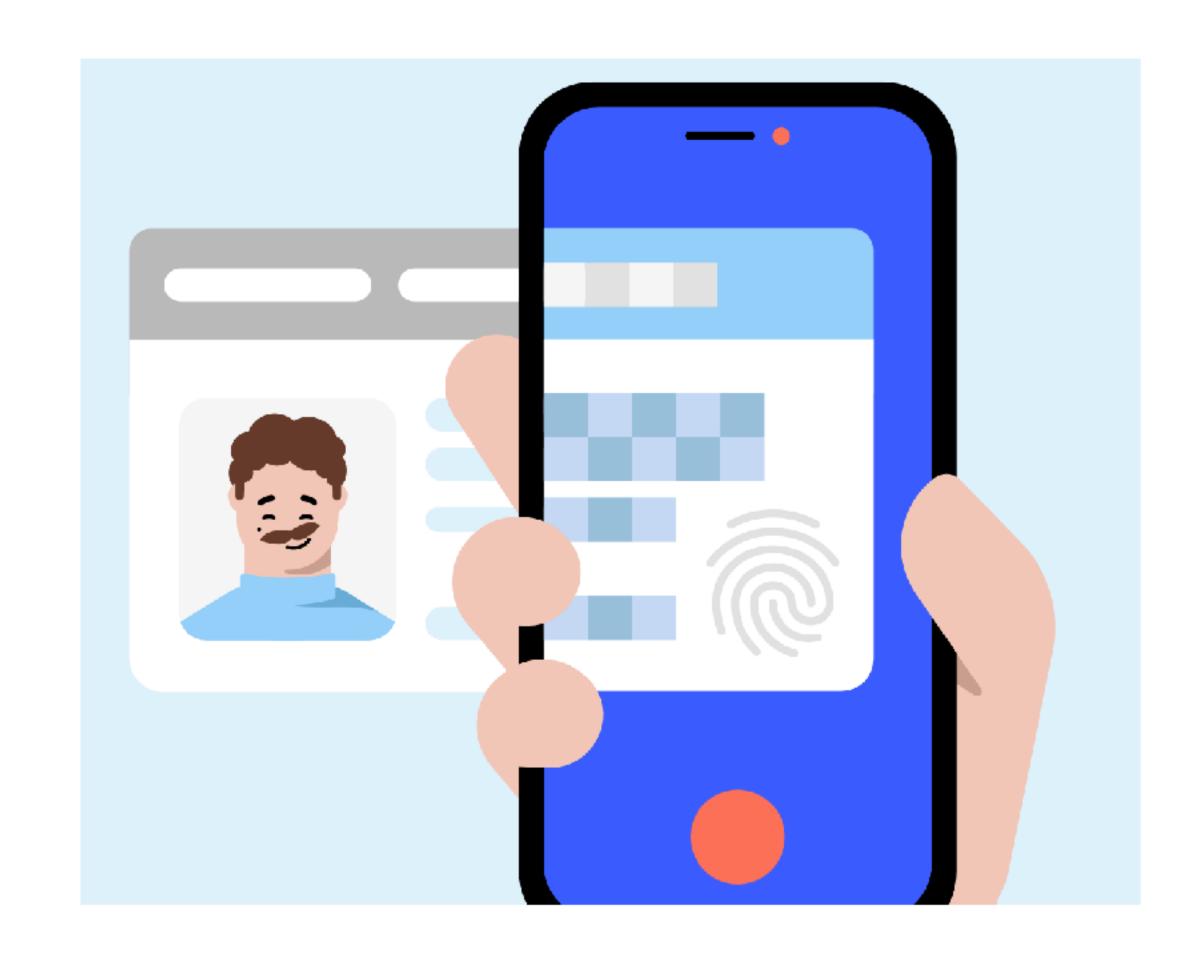
Aside: Is Putin's popularity calculation private? List Experiment

- Split users randomly into two groups
- Design a set of options very similar to the one you actually care about
- To control only ask about the rest. To the treatment include your option.
- Does this satisfy DP?





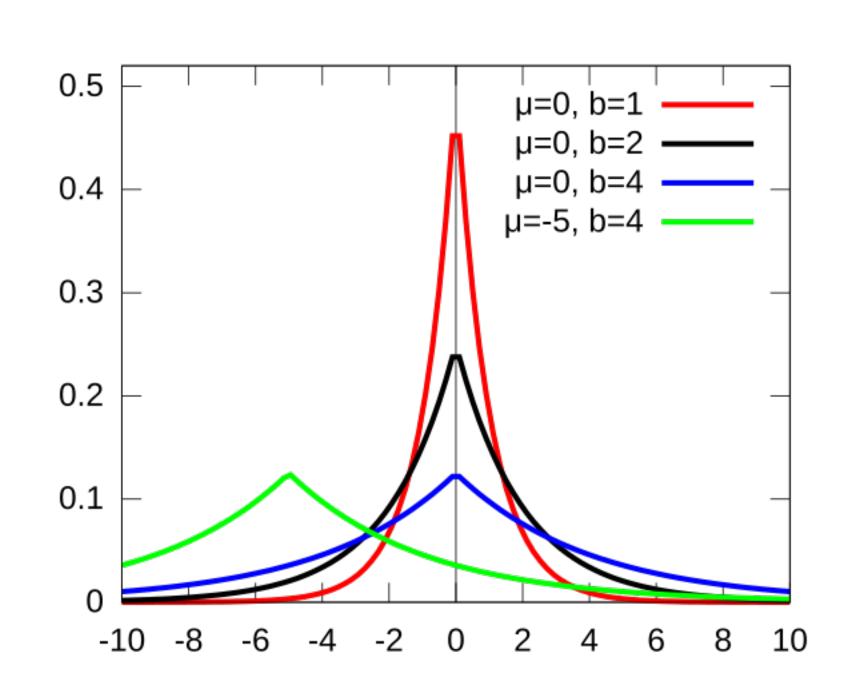
Algorithms for Differential Privacy



Just add Laplace noise

$$\forall y, \forall \text{ similar } D, D': \frac{Pr[A(D) = y]}{Pr[A(D') = y]} \leq \exp(\varepsilon)$$

- Suppose A(D) = 0, A(D') = 1.
- Release $\hat{y} = y + \text{Laplace}(0, \varepsilon^{-1})$
- $z \sim \text{Laplace}(\mu, b) \Rightarrow p(z) = \frac{1}{2b} e^{\frac{-|z-\mu|}{b}}$



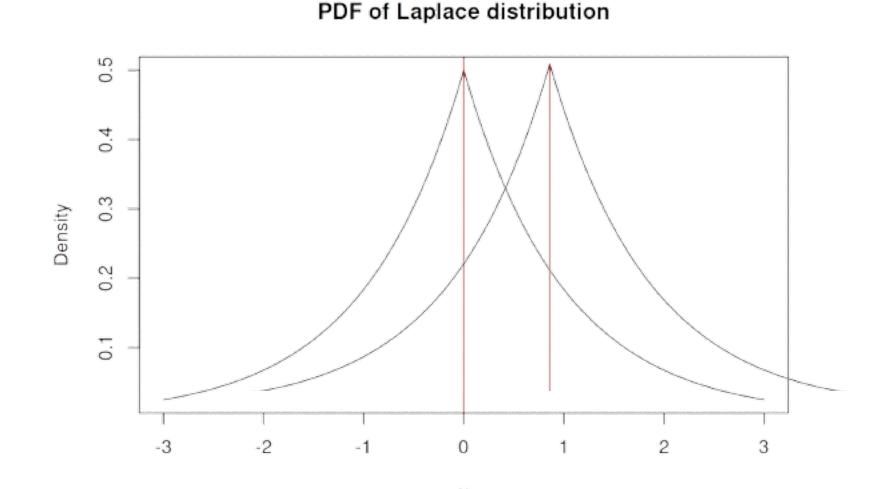
Just add Laplace noise

$$\forall y, \forall \text{ similar } D, D': \qquad \frac{Pr[A(D) = y]}{Pr[A(D') = y]} \leq \exp(\varepsilon)$$

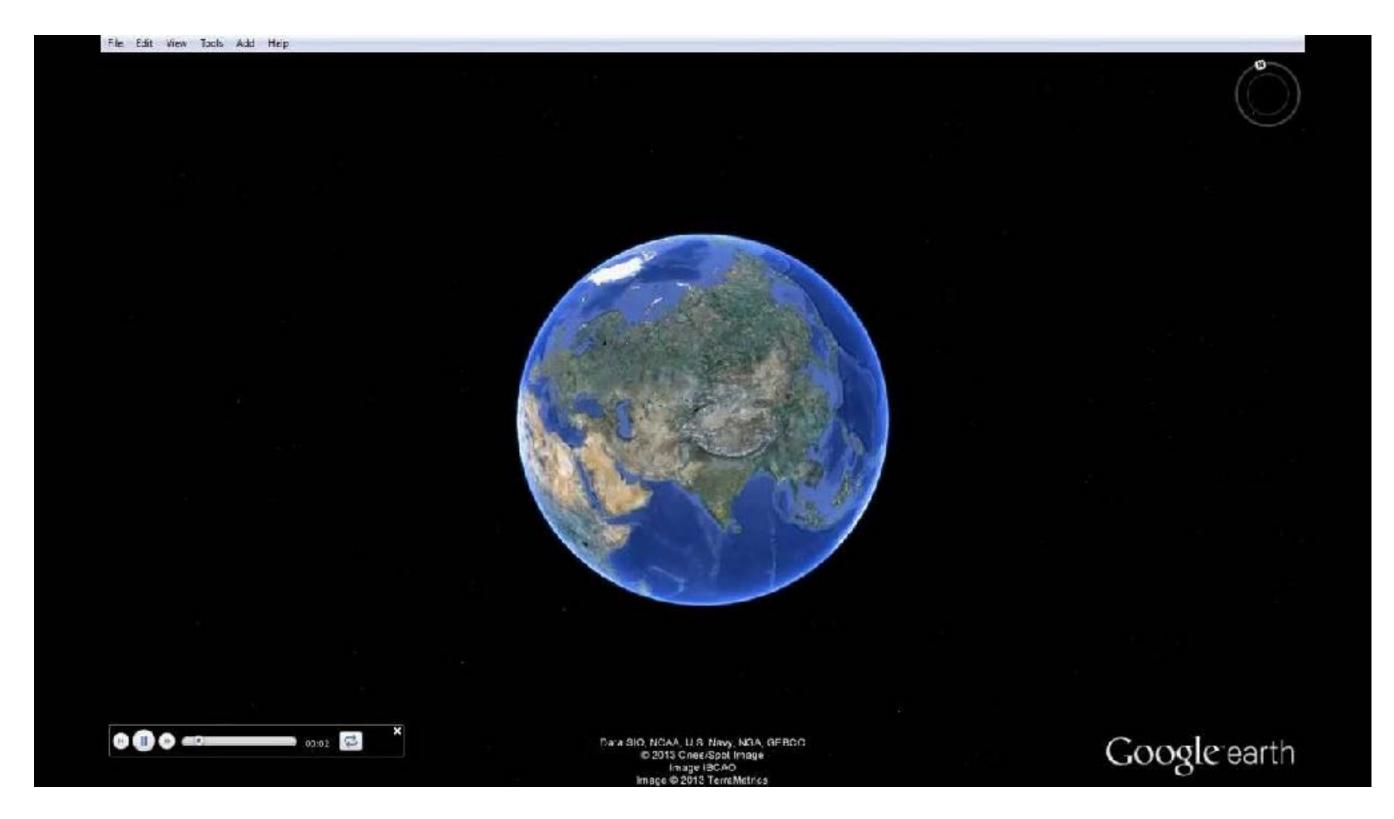
- Suppose A(D) = 0, A(D') = 1. Release $\hat{y} = y + \text{Laplace}(0, \varepsilon^{-1})$
- $Pr[\hat{y} | y = 0] = Laplace(0, \varepsilon^{-1})$ and $Pr[\hat{y} | y = 1] = Laplace(1, \varepsilon^{-1})$

$$Pr[A(D) = y] = \frac{e^{-\varepsilon|y|}}{e^{-\varepsilon|y-1|}} = e^{\varepsilon}$$

$$Pr[A(D') = y] = \frac{e^{-\varepsilon|y|}}{e^{-\varepsilon|y-1|}} = e^{\varepsilon}$$



Differentially Private Algorithms Sensitivity



- I release average income at different zoom levels. Added Lap(0,1).
- Do they all leak same amount of privacy?

Sensitivity and Laplace mechanism

• **Definition:** Sensitivity of a function $f:(x_1,\cdots,x_n)\mapsto (y_1,\cdots,y_k)$ with respect to a norm $\|\cdot\|$ is

$$\Delta f = \max_{\text{similar datasets } D, D'} ||f(D) - f(D')||$$

Theorem

Suppose f is Δ -sensitive with respect to $\|\cdot\|_1$. Then, the following satisfies ε -DP:

$$[A(D)]_i = [f(D)]_i + \text{Laplace}(0, \Delta \varepsilon^{-1})$$

Sensitivity and Laplace mechanism

• **Definition:** Sensitivity of a function $f:(x_1, \dots, x_n) \mapsto (y_1, \dots, y_k)$ with respect to a norm $\|\cdot\|$ is

$$\Delta f = \max_{\text{similar datasets } D, D'} ||f(D) - f(D')||$$

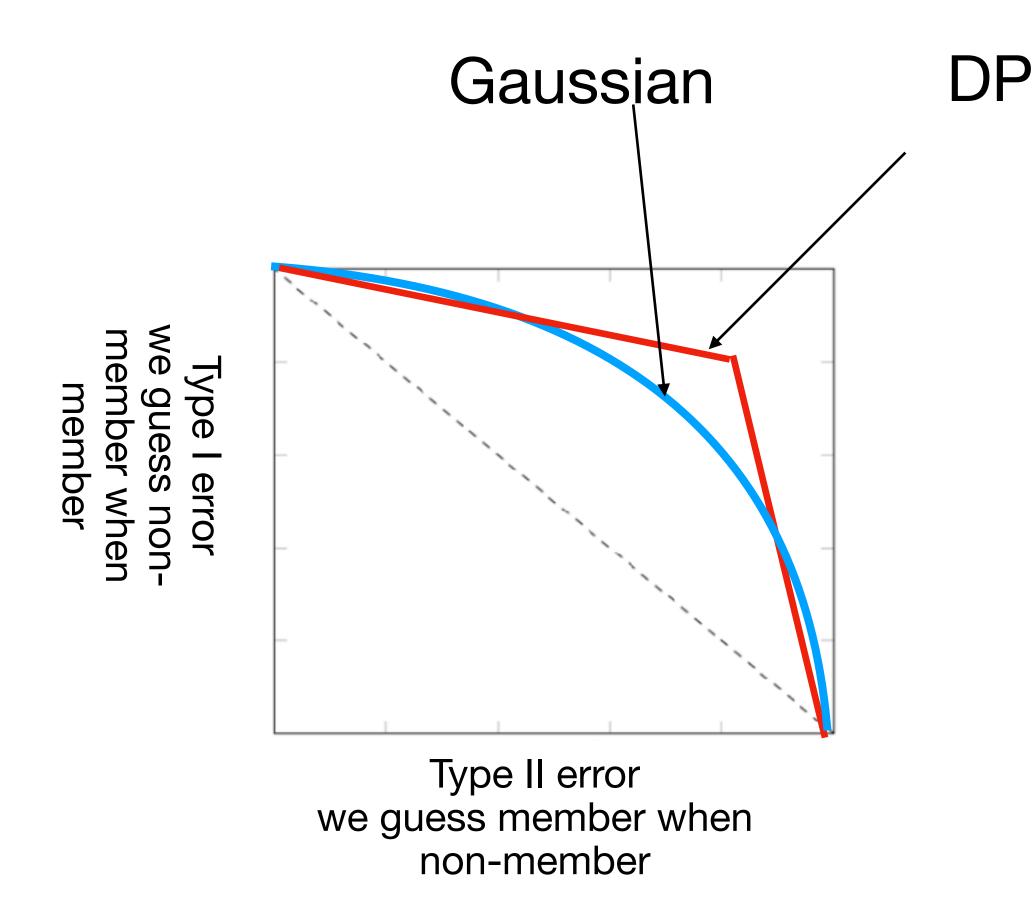
- How much noise should we add if we have Δ -sensitivity wrt $\|\cdot\|_{\infty}$
- What about Δ -sensitivity wrt $\|\cdot\|_2$
- Laplace mechanism is great for functions with small \mathcal{C}_1 sensitivity, not so much for small \mathcal{C}_2 sensitivity

Gaussian mechanism

- Suppose A(D) = 0, A(D') = 1.
- Release $\hat{y} = y + \text{Gaussian}(0, \varepsilon^{-1})$
- $z \sim \text{Gaussian}(\mu, \sigma^2) \Rightarrow p(z) \propto \frac{1}{\sigma} e^{-\frac{1}{2}(\frac{z-\mu}{\sigma})^2}$
- $Pr[\hat{y} | y = 0] = Gaussian(0, \varepsilon^{-1})$ and $Pr[\hat{y} | y = 1] = Gaussian(1, \varepsilon^{-1})$

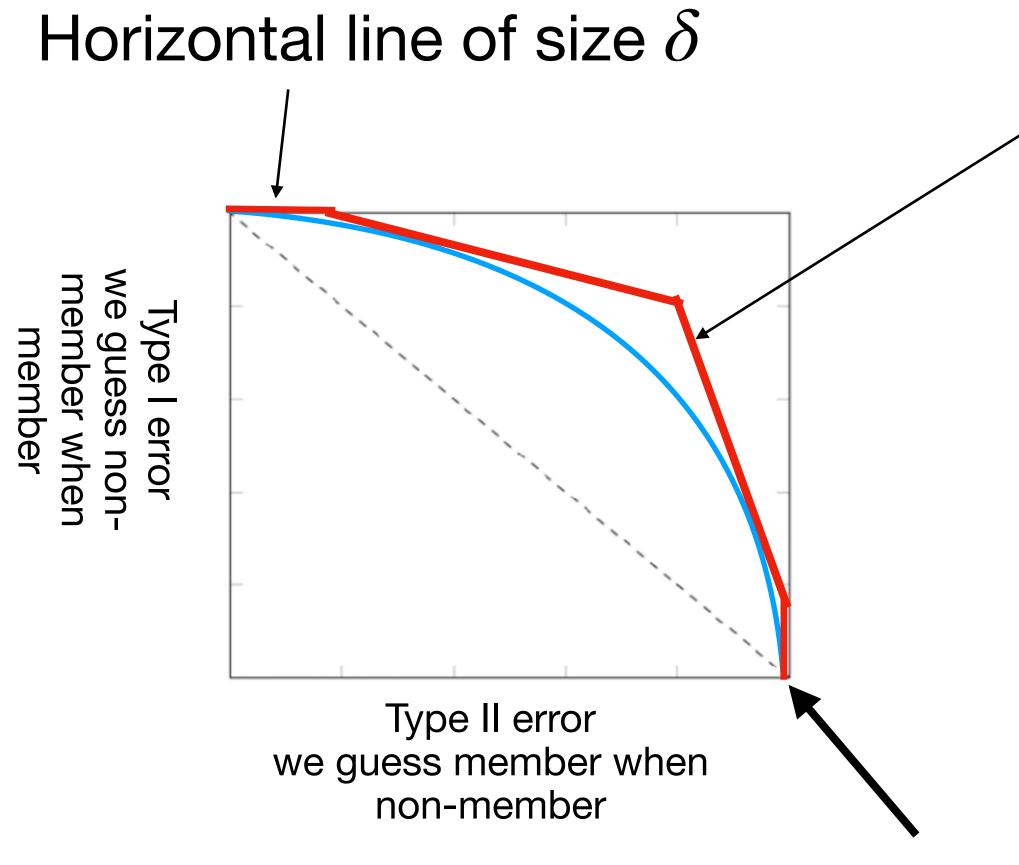
$$\frac{Pr[A(D) = y]}{Pr[A(D') = y]} = ? \text{ What happens at the tails?}$$

Visualizing tradeoff curve of DP and Gaussian mechanism



- At the edges, the slope of gaussian mechanism is vertical
- Impossible to get DP guarantee for any value of ε
- Does this mean Gaussian mechanism is not private?

Approximate DP



Approximate (ε, δ) -DP

- Add flat lines of length δ at the edges to make some space for Gaussian mechanism
- Now chance for Gaussian mechanism to show privacy!

Vertical line of size δ

Approximate Differential Privacy

(ε, δ) -Differential Privacy:

Let us draw a variable $t \sim A(D)$. Then the privacy loss random variable:

$$\mathcal{L}_{D,D'} := \ln \left(\frac{Pr[A(D) = t]}{Pr[A(D') = t]} \right)$$

A satisfies (ε, δ) -DP iff for any neighboring datasets $D, D' \in \chi^n$ we have

$$Pr\left[\mathcal{L}_{D,D'} \geq \varepsilon\right] \leq \delta$$

- With δ probability, arbitrarily bad things can happen.
- Ideally δ is chosen very small $\delta \leq n^{-1}$, or more common in fixed to 10^{-5} .

Gaussian mechanism

- Suppose A(D) = 0, A(D') = 1. Release $\hat{y} = y + \text{Gaussian}(0, \varepsilon^{-1})$
- $z \sim \text{Gaussian}(\mu, \sigma^2) \Rightarrow p(z) \propto \frac{1}{\sigma} e^{-\frac{1}{2}(\frac{z-\mu}{\sigma})^2}$
- $Pr[\hat{y} | y = 0] = Gaussian(0, \varepsilon^{-1})$ and $Pr[\hat{y} | y = 1] = Gaussian(1, \varepsilon^{-1})$

•
$$\frac{Pr[A(D) = y]}{Pr[A(D') = y]} = ? \text{ what happens now?}$$